

# EC400: DPDE

Class #1

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# Problem 1

# Problem 1

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Suppose that an agent gets utility not only from consumption over  $T$  periods of her life, but also from leaving a bequest to its descendants

$$\sum_{t=0}^T \beta^t \ln(C_t) + \eta \beta^T \ln(B_{T+1})$$

and is subject to a standard budget constraint

$$B_{t+1} = RB_t + Y_t - C_t.$$

# Problem 1

## Question 1

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1. Is the additional constraint  $B_{T+1} \geq 0$  discussed in the lecture binding in this case?

# Problem 1

## Question 1: Solution

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- $B_{T+1} \geq 0$  is **not binding** since

$$U \left( \{C_t\}_{t=0}^T, B_{T+1} \right) \xrightarrow{B_{T+1} \rightarrow 0} -\infty \implies B_{T+1}^* > 0.$$

# Problem 1

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2. Derive the optimality conditions and provide intuition for the terminal condition.

# Problem 1

## Question 2: Solution

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- Lagrangian:

$$\mathcal{L} = \sum_{t=0}^T \beta^t \ln(C_t) + \eta \beta^T \ln(B_{T+1}) + \sum_{t=0}^T \lambda_t (RB_t + Y_t - C_t - B_{t+1}) + \mu B_{T+1}$$

where  $\mathcal{L} = \mathcal{L} \left( \{C_t, B_{t+1}, \lambda_t\}_{t=0}^T, \mu \mid \{Y_t\}_{t=0}^T, R, \beta, \eta \right)$ .



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● FOC:

$$[C_t] \quad \beta^t \frac{1}{C_t} - \lambda_t = 0, \quad \forall t \in \{0, \dots, T\},$$

$$[B_{t+1}] \quad -\lambda_t + R\lambda_{t+1} = 0, \quad \forall t \in \{0, \dots, T-1\},$$

$$[B_{T+1}] \quad \eta\beta^T \frac{1}{B_{T+1}} - \lambda_T = 0.$$

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● Solving:

# Problem 1

## Question 2: Solution

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- Solving:

- **Euler equations:** From  $[C_t]$  and  $[B_{t+1}]$ ,  
 $\forall t \in \{0, \dots, T-1\}, \beta^t \frac{1}{C_t} = R\beta^{t+1} \frac{1}{C_{t+1}} \iff C_{t+1} = \beta R C_t.$

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- Solving:

- **Euler equations:** From  $[C_t]$  and  $[B_{t+1}]$ ,  
 $\forall t \in \{0, \dots, T-1\}, \beta^t \frac{1}{C_t} = R\beta^{t+1} \frac{1}{C_{t+1}} \iff C_{t+1} = \beta R C_t.$

- **Terminal condition:** From  $[C_T]$  and  $[B_{T+1}]$ ,  
 $\beta^T \frac{1}{C_T} = \eta \beta^T \frac{1}{B_{T+1}} \iff B_{T+1} = \eta C_T.$

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- Solving:

- **Euler equations:** From  $[C_t]$  and  $[B_{t+1}]$ ,  
 $\forall t \in \{0, \dots, T-1\}, \beta^t \frac{1}{C_t} = R\beta^{t+1} \frac{1}{C_{t+1}} \iff C_{t+1} = \beta R C_t.$

- **Terminal condition:** From  $[C_T]$  and  $[B_{T+1}]$ ,  
 $\beta^T \frac{1}{C_T} = \eta \beta^T \frac{1}{B_{T+1}} \iff B_{T+1} = \eta C_T.$

- **Intuition for the terminal condition:** In the last period, agent equalizes marginal utility from spending money on consumption and leaving it as a bequest.

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3. Solve for the optimal consumption  $C_0$  and bequest  $B_{T+1}$  assuming  $B_0 = 0$  and  $Y_t = Y$ .

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## Question 3: Solution

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- Iterating the budget constraint forward:

$$\sum_{t=0}^T R^{-t} (C_t - Y) + R^{-T} B_{T+1} = 0.$$

► details

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## Question 3: Solution

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- Iterating the budget constraint forward:

$$\sum_{t=0}^T R^{-t} (C_t - Y) + R^{-T} B_{T+1} = 0.$$

► details

- From the optimality conditions:  $C_t = (R\beta)^t C_0$  for  $t \in \{0, \dots, T\}$   
and  $B_{T+1} = \eta (R\beta)^T C_0$ .

► details



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- Iterating the budget constraint forward:

$$\sum_{t=0}^T R^{-t} (C_t - Y) + R^{-T} B_{T+1} = 0.$$

► details

- From the optimality conditions:  $C_t = (R\beta)^t C_0$  for  $t \in \{0, \dots, T\}$  and  $B_{T+1} = \eta (R\beta)^T C_0$ .

► details

- Substitute into the intertemporal BC and solve for  $C_0$  to obtain:

$$C_0 = \frac{1-\beta}{1+\eta\beta^T - (1+\eta)\beta^{T+1}} \frac{R-R^{-T}}{R-1} Y.$$

► details

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4. What happens to the optimal bequest when  $T \rightarrow \infty$  if  $\beta R = 1$ ? Explain.

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- Taking the limit as  $T \rightarrow \infty$  on both sides of the expression for  $B_{T+1}$  and using the assumptions  $\beta < 1$ ,  $R > 1$ , and  $\beta R = 1$ :

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- Taking the limit as  $T \rightarrow \infty$  on both sides of the expression for  $B_{T+1}$  and using the assumptions  $\beta < 1$ ,  $R > 1$ , and  $\beta R = 1$ :

$$B_{T+1} \xrightarrow{T \rightarrow \infty} \eta \frac{1 - \beta}{1 + 0 + 0} \frac{R - 0}{R - 1} Y$$

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- Taking the limit as  $T \rightarrow \infty$  on both sides of the expression for  $B_{T+1}$  and using the assumptions  $\beta < 1$ ,  $R > 1$ , and  $\beta R = 1$ :

$$\begin{aligned} B_{T+1} &\xrightarrow{T \rightarrow \infty} \eta \frac{1 - \beta}{1 + 0 + 0} \frac{R - 0}{R - 1} Y \\ &= \eta \frac{R - 1}{R} \frac{R}{R - 1} Y \end{aligned}$$

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- Taking the limit as  $T \rightarrow \infty$  on both sides of the expression for  $B_{T+1}$  and using the assumptions  $\beta < 1$ ,  $R > 1$ , and  $\beta R = 1$ :

$$\begin{aligned} B_{T+1} &\xrightarrow{T \rightarrow \infty} \eta \frac{1 - \beta}{1 + 0 + 0} \frac{R - 0}{R - 1} Y \\ &= \eta \frac{R - 1}{R} \frac{R}{R - 1} Y \\ &= \eta Y. \end{aligned}$$

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### ● Intuition:

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## Question 4: Solution

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- **Intuition:**

- Utility from the bequest is isomorphic to utility from consumption in a period far in the future.



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### ● Intuition:

- Utility from the bequest is isomorphic to utility from consumption in a period far in the future.
- $\beta R = 1 \implies$  agent perfectly smooths consumption (i.e.,  $C_t = C \forall t$ ) and also leaves a positive bequest.

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## Problem 2

# Problem 2

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Consider an agent with a CRRA utility

$$\int_0^T e^{-\rho t} \frac{C_t^{1-\sigma} - 1}{1-\sigma} dt$$

and a budget constraint

$$\dot{B}_t = rB_t - C_t,$$

where labor income is zero,  $r = \rho$ , and  $B_0 > 0$ .

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1. Show that the CRRA utility converges to  $u(C) = \ln(C)$  in the limit  $\sigma \rightarrow 1$ . Focus on this limit for the rest of the problem.

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- Using L'Hôpital's rule and recalling that  $\frac{da^x}{dx} = \ln(a)a^x$ ,

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- Using L'Hôpital's rule and recalling that  $\frac{da^x}{dx} = \ln(a)a^x$ ,

$$\lim_{\sigma \rightarrow 1} u(C) = \lim_{\sigma \rightarrow 1} \frac{C^{1-\sigma} - 1}{1 - \sigma}$$

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- Using L'Hôpital's rule and recalling that  $\frac{da^x}{dx} = \ln(a)a^x$ ,

$$\lim_{\sigma \rightarrow 1} u(C) = \lim_{\sigma \rightarrow 1} \frac{C^{1-\sigma} - 1}{1 - \sigma}$$

$$\stackrel{\text{L'H}}{=} \lim_{\sigma \rightarrow 1} \frac{-\ln(C) C^{1-\sigma}}{-1}$$

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- Using L'Hôpital's rule and recalling that  $\frac{da^x}{dx} = \ln(a)a^x$ ,

$$\begin{aligned}\lim_{\sigma \rightarrow 1} u(C) &= \lim_{\sigma \rightarrow 1} \frac{C^{1-\sigma} - 1}{1 - \sigma} \\ &\stackrel{\text{L'H}}{=} \lim_{\sigma \rightarrow 1} \frac{-\ln(C) C^{1-\sigma}}{-1} \\ &= \ln(C).\end{aligned}$$



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- Alternatively, using the fact that  $x = e^{\ln(x)}$  and L'Hôspital's rule,

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- Alternatively, using the fact that  $x = e^{\ln(x)}$  and L'Hôspital's rule,

$$\lim_{\sigma \rightarrow 1} u(C) = \lim_{\sigma \rightarrow 1} \frac{C^{1-\sigma} - 1}{1 - \sigma}$$

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- Alternatively, using the fact that  $x = e^{\ln(x)}$  and L'Hôspital's rule,

$$\begin{aligned}\lim_{\sigma \rightarrow 1} u(C) &= \lim_{\sigma \rightarrow 1} \frac{C^{1-\sigma} - 1}{1 - \sigma} \\ &= \lim_{\sigma \rightarrow 1} \frac{e^{\ln(C^{1-\sigma})} - 1}{1 - \sigma}\end{aligned}$$

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- Alternatively, using the fact that  $x = e^{\ln(x)}$  and L'Hôspital's rule,

$$\begin{aligned}\lim_{\sigma \rightarrow 1} u(C) &= \lim_{\sigma \rightarrow 1} \frac{C^{1-\sigma} - 1}{1 - \sigma} \\ &= \lim_{\sigma \rightarrow 1} \frac{e^{\ln(C^{1-\sigma})} - 1}{1 - \sigma} \\ &= \lim_{\sigma \rightarrow 1} \frac{e^{(1-\sigma)\ln(C)} - 1}{1 - \sigma}\end{aligned}$$

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- Alternatively, using the fact that  $x = e^{\ln(x)}$  and L'Hôspital's rule,

$$\lim_{\sigma \rightarrow 1} u(C) = \lim_{\sigma \rightarrow 1} \frac{C^{1-\sigma} - 1}{1 - \sigma}$$

$$= \lim_{\sigma \rightarrow 1} \frac{e^{\ln(C^{1-\sigma})} - 1}{1 - \sigma}$$

$$= \lim_{\sigma \rightarrow 1} \frac{e^{(1-\sigma)\ln(C)} - 1}{1 - \sigma}$$

$$\stackrel{\text{L'H}}{=} \frac{-\ln(C) e^{(1-\sigma)\ln(C)}}{-1}$$

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- Alternatively, using the fact that  $x = e^{\ln(x)}$  and L'Hôspital's rule,

$$\begin{aligned}\lim_{\sigma \rightarrow 1} u(C) &= \lim_{\sigma \rightarrow 1} \frac{C^{1-\sigma} - 1}{1 - \sigma} \\&= \lim_{\sigma \rightarrow 1} \frac{e^{\ln(C^{1-\sigma})} - 1}{1 - \sigma} \\&= \lim_{\sigma \rightarrow 1} \frac{e^{(1-\sigma)\ln(C)} - 1}{1 - \sigma} \\&\stackrel{\text{L'H}}{=} \frac{-\ln(C) e^{(1-\sigma)\ln(C)}}{-1} \\&= \ln(C).\end{aligned}$$

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2. Write down the Hamiltonian and derive the optimality conditions.

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- Hamiltonian:

$$\mathcal{H}_t = e^{-\rho t} \ln(C_t) + \lambda_t (rB_t - C_t)$$



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## Question 2: Solution

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- Hamiltonian:

$$\mathcal{H}_t = e^{-\rho t} \ln(C_t) + \lambda_t (rB_t - C_t)$$

- Maximum principle:

$$[C_t] \quad \frac{\partial \mathcal{H}_t}{\partial C_t} = 0 \iff e^{-\rho t} \frac{1}{C_t} - \lambda_t = 0$$

$$[B_t] \quad \frac{\partial \mathcal{H}_t}{\partial B_t} = -\dot{\lambda}_t \iff r\lambda_t = -\dot{\lambda}_t$$

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- Optimality conditions:

# Problem 2

## Question 2: Solution

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- Optimality conditions:

- From  $[C_t]$ :  $\lambda_t = \frac{e^{-\rho t}}{C_t} \implies -\dot{\lambda}_t = \frac{e^{-\rho t}}{C_t} \left[ \rho + \frac{\dot{C}_t}{C_t} \right].$

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- Optimality conditions:

- From  $[C_t]$ :  $\lambda_t = \frac{e^{-\rho t}}{C_t} \implies -\dot{\lambda}_t = \frac{e^{-\rho t}}{C_t} \left[ \rho + \frac{\dot{C}_t}{C_t} \right].$

- Plugging into  $[B_t]$ :  
$$r \frac{e^{-\rho t}}{C_t} = \frac{e^{-\rho t}}{C_t} \left[ \rho + \frac{\dot{C}_t}{C_t} \right] \iff (r - \rho) = \frac{\dot{C}_t}{C_t} = 0 \implies C_t = C_0 e^{(r-\rho)t}.$$

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- Optimality conditions:

- From  $[C_t]$ :  $\lambda_t = \frac{e^{-\rho t}}{C_t} \implies -\dot{\lambda}_t = \frac{e^{-\rho t}}{C_t} \left[ \rho + \frac{\dot{C}_t}{C_t} \right].$

- Plugging into  $[B_t]$ :  
$$r \frac{e^{-\rho t}}{C_t} = \frac{e^{-\rho t}}{C_t} \left[ \rho + \frac{\dot{C}_t}{C_t} \right] \iff (r - \rho) = \frac{\dot{C}_t}{C_t} = 0 \implies C_t = C_0 e^{(r-\rho)t}.$$

- Using the assumption  $r = \rho$ :  $C_t = C_0 \forall t \in [0, T].$

► details

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- Optimality conditions:

- From  $[C_t]$ :  $\lambda_t = \frac{e^{-\rho t}}{C_t} \implies -\dot{\lambda}_t = \frac{e^{-\rho t}}{C_t} \left[ \rho + \frac{\dot{C}_t}{C_t} \right].$

- Plugging into  $[B_t]$ :  
$$r \frac{e^{-\rho t}}{C_t} = \frac{e^{-\rho t}}{C_t} \left[ \rho + \frac{\dot{C}_t}{C_t} \right] \iff (r - \rho) = \frac{\dot{C}_t}{C_t} = 0 \implies C_t = C_0 e^{(r-\rho)t}.$$

- Using the assumption  $r = \rho$ :  $C_t = C_0 \forall t \in [0, T].$

► details

- Transversality condition:

$$\lambda_T B_T = 0 \iff \frac{e^{-\rho T}}{C_0} B_T = 0 \iff B_T = 0.$$

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3. Obtain the intertemporal budget constraint and solve for the optimal consumption.

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- Multiplying by  $e^{-rt}$  on both sides of the flow BC  $\dot{B}_t = rB_t - C_t$ , integrating on both sides and evaluating at  $t = T$ :



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## Question 3: Solution

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- Multiplying by  $e^{-rt}$  on both sides of the flow BC  $\dot{B}_t = rB_t - C_t$ , integrating on both sides and evaluating at  $t = T$ :

$$e^{-rt} \dot{B}_t - re^{-rt} B_t = -e^{-rt} C_t$$

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- Multiplying by  $e^{-rt}$  on both sides of the flow BC  $\dot{B}_t = rB_t - C_t$ , integrating on both sides and evaluating at  $t = T$ :

$$e^{-rt} \dot{B}_t - re^{-rt} B_t = -e^{-rt} C_t$$

$$\iff d[e^{-rt} B_t] = -e^{-rt} C_t dt$$

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- Multiplying by  $e^{-rt}$  on both sides of the flow BC  $\dot{B}_t = rB_t - C_t$ , integrating on both sides and evaluating at  $t = T$ :

$$e^{-rt} \dot{B}_t - re^{-rt} B_t = -e^{-rt} C_t$$

$$\iff d[e^{-rt} B_t] = -e^{-rt} C_t dt$$

$$\iff e^{-rt} B_t = B_0 - \int_0^t e^{-rs} C_s ds$$

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- Multiplying by  $e^{-rt}$  on both sides of the flow BC  $\dot{B}_t = rB_t - C_t$ , integrating on both sides and evaluating at  $t = T$ :

$$e^{-rt} \dot{B}_t - re^{-rt} B_t = -e^{-rt} C_t$$

$$\iff d[e^{-rt} B_t] = -e^{-rt} C_t dt$$

$$\iff e^{-rt} B_t = B_0 - \int_0^t e^{-rs} C_s ds$$

$$\implies \underbrace{e^{-rT} B_T}_{0 \text{ by TVC}} = B_0 - \int_0^T e^{-rs} C_s ds.$$

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- Using  $C_s = C_0 \forall s \in [0, T]$  and solving for  $C_0$ :

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- Using  $C_s = C_0 \forall s \in [0, T]$  and solving for  $C_0$ :

$$\int_0^T e^{-rs} C_0 ds = B_0$$

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- Using  $C_s = C_0 \forall s \in [0, T]$  and solving for  $C_0$ :

$$\int_0^T e^{-rs} C_0 ds = B_0$$

$$\Leftrightarrow C_0 \left[ -\frac{1}{r} e^{-rs} \right] \Big|_{s=0}^T = B_0$$

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- Using  $C_s = C_0 \forall s \in [0, T]$  and solving for  $C_0$ :

$$\int_0^T e^{-rs} C_0 ds = B_0$$

$$\Leftrightarrow C_0 \left[ -\frac{1}{r} e^{-rs} \right] \Big|_{s=0}^T = B_0$$

$$\Leftrightarrow C_0 = \frac{rB_0}{1 - e^{-rT}}$$



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- Using  $C_s = C_0 \forall s \in [0, T]$  and solving for  $C_0$ :

$$\int_0^T e^{-rs} C_0 ds = B_0$$

$$\iff C_0 \left[ -\frac{1}{r} e^{-rs} \right] \Big|_{s=0}^T = B_0$$

$$\iff C_0 = \frac{rB_0}{1 - e^{-rT}}$$

- Finally, using  $r = \rho \implies C_t = C_0 \forall t \in [0, T]$ :

$$C_t = \frac{\rho B_0}{1 - e^{-\rho T}} \forall t \in [0, T].$$

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4. Suppose the agent can choose not only consumption path, but also the length of life  $T$ . Assuming utility is zero for  $t > T$  and the agent cannot leave any debt, solve for the optimal value of  $T$ .

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## Question 4: Solution

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- Substituting the optimal consumption path into the objective function and integrating:

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- Substituting the optimal consumption path into the objective function and integrating:

$$\int_0^T e^{\rho t} \ln \left( \frac{\rho B_0}{1 - e^{-\rho T}} \right) dt = \left[ \ln(\rho B_0) - \ln(1 - e^{-\rho T}) \right] \left( -\frac{e^{-\rho t}}{\rho} \right) \Big|_{t=0}^T$$

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- Substituting the optimal consumption path into the objective function and integrating:

$$\begin{aligned}\int_0^T e^{\rho t} \ln \left( \frac{\rho B_0}{1 - e^{-\rho T}} \right) dt &= \left[ \ln(\rho B_0) - \ln(1 - e^{-\rho T}) \right] \left( -\frac{e^{-\rho t}}{\rho} \right) \Big|_{t=0}^T \\ &= \left[ \ln(\rho B_0) - \ln(1 - e^{-\rho T}) \right] \left( -\frac{e^{-\rho T} + 1}{\rho} \right).\end{aligned}$$

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- Substituting the optimal consumption path into the objective function and integrating:

$$\begin{aligned}\int_0^T e^{\rho t} \ln \left( \frac{\rho B_0}{1 - e^{-\rho T}} \right) dt &= \left[ \ln(\rho B_0) - \ln(1 - e^{-\rho T}) \right] \left( -\frac{e^{-\rho t}}{\rho} \right) \Big|_{t=0}^T \\ &= \left[ \ln(\rho B_0) - \ln(1 - e^{-\rho T}) \right] \left( -\frac{e^{-\rho T} + 1}{\rho} \right).\end{aligned}$$

- The problem is:

$$\max_{T \in \mathbb{R}_+^2} \left[ \ln(\rho B_0) - \ln(1 - e^{-\rho T}) \right] (1 - e^{-\rho T}).$$

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- Taking FOC and solving for  $T^*$ , we find:

$$T^* = \begin{cases} -\frac{1}{\rho} \ln(1 - \rho B_0 e^{-1}) & \text{if } \rho B_0 e^{-1} < 1 \\ +\infty & \text{otherwise} \end{cases},$$

where  $-\rho B_0 e^{-1} < 0 \implies \ln(1 - \rho B_0 e^{-1}) < 0$ .

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5. Derive the optimality condition for  $T$  using a perturbation argument.



# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Starting from the, suppose the agent increases  $T$  by  $dT = \Delta > 0$ .

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Starting from the, suppose the agent increases  $T$  by  $dT = \Delta > 0$ .
  - Given  $\dot{C}_t = 0$ , the agent spends  $C_T \Delta$  over this period.

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Starting from the, suppose the agent increases  $T$  by  $dT = \Delta > 0$ .
  - Given  $\dot{C}_t = 0$ , the agent spends  $C_T \Delta$  over this period.
  - This requires a proportionate increase in  $B_T$ .

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Starting from the, suppose the agent increases  $T$  by  $dT = \Delta > 0$ .
  - Given  $\dot{C}_t = 0$ , the agent spends  $C_T \Delta$  over this period.
  - This requires a proportionate increase in  $B_T$ .
  - According to the BC:

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Starting from the, suppose the agent increases  $T$  by  $dT = \Delta > 0$ .
  - Given  $\dot{C}_t = 0$ , the agent spends  $C_T \Delta$  over this period.
  - This requires a proportionate increase in  $B_T$ .
  - According to the BC:

$$B_T = e^{rT} B_0 - \frac{1}{r} (1 - e^{-rT}) C_T$$

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Starting from the, suppose the agent increases  $T$  by  $dT = \Delta > 0$ .
  - Given  $\dot{C}_t = 0$ , the agent spends  $C_T \Delta$  over this period.
  - This requires a proportionate increase in  $B_T$ .
  - According to the BC:

$$B_T = e^{rT} B_0 - \frac{1}{r} (1 - e^{-rT}) C_T$$
$$\implies \underbrace{dB_T}_{C_T \Delta} = e^{rT} B_0 - \frac{1}{r} (1 - e^{-rT}) dC_T$$

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Starting from the, suppose the agent increases  $T$  by  $dT = \Delta > 0$ .
  - Given  $\dot{C}_t = 0$ , the agent spends  $C_T \Delta$  over this period.
  - This requires a proportionate increase in  $B_T$ .
  - According to the BC:

$$\begin{aligned} B_T &= e^{rT} B_0 - \frac{1}{r} (1 - e^{-rT}) C_T \\ \implies \underbrace{dB_T}_{C_T \Delta} &= e^{rT} B_0 - \frac{1}{r} (1 - e^{-rT}) dC_T \\ \iff dC_T &= -\frac{rC_T \Delta}{e^{rT} - 1}. \end{aligned}$$

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

**Problem 2**

Problem 3



# Problem 2

## Question 5: Solution

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Problem 1

Problem 2

Problem 3

• Thus,

$$dC_t = -\frac{rC_T\Delta}{e^{rT}-1} \forall t \in [0, T]$$

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Thus,

$$dC_t = -\frac{rC_T\Delta}{e^{rT}-1} \forall t \in [0, T]$$

- Given  $r = \rho$ , the net change in utility is

$$e^{-\rho T} u(C_T)\Delta + \int_0^T e^{-\rho t} u'(C_T) dC_T dt = e^{-\rho T} [\ln(C_T) - 1] \Delta.$$

► details

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

**Problem 2**

Problem 3

- Under the interior solution, we must have

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Under the interior solution, we must have

$$du = 0$$

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Under the interior solution, we must have

$$du = 0 \iff \ln(C_T) = 1$$

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Under the interior solution, we must have

$$du = 0 \iff \ln(C_T) = 1 \iff C_T = e.$$

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Under the interior solution, we must have

$$du = 0 \iff \ln(C_T) = 1 \iff C_T = e.$$

- Finally, combining with our previous expression for  $C_T$ ,

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Under the interior solution, we must have

$$du = 0 \iff \ln(C_T) = 1 \iff C_T = e.$$

- Finally, combining with our previous expression for  $C_T$ ,

$$\frac{\rho B_0}{1 - e^{-\rho T}} = e$$



# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Under the interior solution, we must have

$$du = 0 \iff \ln(C_T) = 1 \iff C_T = e.$$

- Finally, combining with our previous expression for  $C_T$ ,

$$\frac{\rho B_0}{1 - e^{-\rho T}} = e$$

$$\iff e^{-\rho T} = 1 - \rho B_0 e^{-1}$$

# Problem 2

## Question 5: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Under the interior solution, we must have

$$du = 0 \iff \ln(C_T) = 1 \iff C_T = e.$$

- Finally, combining with our previous expression for  $C_T$ ,

$$\frac{\rho B_0}{1 - e^{-\rho T}} = e$$

$$\iff e^{-\rho T} = 1 - \rho B_0 e^{-1}$$

$$\iff T = -\frac{1}{\rho} \ln(1 - \rho B_0 e^{-1}).$$

---

# Problem 3

# Problem 3

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

Consider the following investment problem. Given initial value of capital  $K_0$ , a firm chooses investment path  $\{I_t\}_{t=0}^{\infty}$  to maximize profits

$$\sum_{t=0}^{\infty} \beta^t \left[ A_t K_t^{\alpha} - I_t - \frac{\phi}{2} \frac{I_t^2}{K_t} \right]$$

subject to the capital law of motion

$$K_{t+1} = (1 - \delta)K_t + I_t,$$

where  $A_t$  is the firm's productivity,  $\alpha \in (0, 1)$ ,  $\phi > 0$  stays for the capital adjustment costs, and  $\delta \in (0, 1)$  is the depreciation rate.

# Problem 3

## Question 1

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

1. Write down the Lagrangian and take the first-order conditions.

# Problem 3

## Question 1: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

● Lagrangian:

$$\mathcal{L} = \sum_{t=0}^{\infty} \beta^t \left[ A_t K_t^\alpha - I_t - \frac{\phi}{2} \frac{I_t^2}{K_t} \right] + \sum_{t=0}^{\infty} \lambda_t \left[ (1 - \delta) K_t + I_t - K_{t+1} \right]$$

# Problem 3

## Question 1: Solution

Class #1

EC400: DPDE

Problem 1

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Problem 3

- Lagrangian:

$$\mathcal{L} = \sum_{t=0}^{\infty} \beta^t \left[ A_t K_t^\alpha - I_t - \frac{\phi}{2} \frac{I_t^2}{K_t} \right] + \sum_{t=0}^{\infty} \lambda_t \left[ (1 - \delta) K_t + I_t - K_{t+1} \right]$$

- FOC:

$$[I_t] \quad -\beta^t \left( 1 + \phi \frac{I_t}{K_t} \right) + \lambda_t = 0$$

$$[K_{t+1}] \quad -\lambda_t + \beta^{t+1} \left( \alpha A_{t+1} K_{t+1}^{\alpha-1} + \frac{\phi}{2} \frac{I_{t+1}^2}{K_{t+1}^2} \right) + \lambda_{t+1} (1 - \delta) = 0$$

# Problem 3

## Question 2

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

2. Use a finite-period version of the model to derive the transversality condition.



# Problem 3

## Question 2: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- In a finite-period version of the model, we add that the firm **cannot leave a negative stock of capital**, i.e.,  $K_{T+1} \geq 0$ .

# Problem 3

## Question 2: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- In a finite-period version of the model, we add that the firm **cannot leave a negative stock of capital**, i.e.,  $K_{T+1} \geq 0$ .
- The Lagrangian of this problem is

$$\mathcal{L} = \sum_{t=0}^T \beta^t \left[ A_t K_t^\alpha - I_t - \frac{\phi}{2} \frac{I_t^2}{K_t} \right] + \sum_{t=0}^T \lambda_t \left[ (1-\delta)K_t + I_t - K_{t+1} \right] + \mu K_{T+1}$$

# Problem 3

## Question 2: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- In a finite-period version of the model, we add that the firm **cannot leave a negative stock of capital**, i.e.,  $K_{T+1} \geq 0$ .

- The Lagrangian of this problem is

$$\mathcal{L} = \sum_{t=0}^T \beta^t \left[ A_t K_t^\alpha - I_t - \frac{\phi}{2} \frac{I_t^2}{K_t} \right] + \sum_{t=0}^T \lambda_t \left[ (1-\delta)K_t + I_t - K_{t+1} \right] + \mu K_{T+1}$$

- The FOC wrt  $K_{T+1}$  is  $-\lambda_T + \mu = 0 \iff \mu = \lambda_T$ .

# Problem 3

## Question 2: Solution

Class #1

EC400: DPDE

Problem 1

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Problem 3

- The complementary slackness condition can then be written as  $\mu K_{t+1} = 0 \iff \lambda_T K_{T+1} = 0$ .

# Problem 3

## Question 2: Solution

Class #1

EC400: DPDE

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Problem 3

- The complementary slackness condition can then be written as  $\mu K_{t+1} = 0 \iff \lambda_T K_{T+1} = 0$ .
- By analogy, the **transversality condition** in the infinite-horizon model is  $\lim_{t \rightarrow \infty} \lambda_t K_{t+1} = 0$ .

# Problem 3

## Question 3

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

3. Derive the analog of the Euler equation, i.e. the optimality condition for capital and investment that does not include  $\lambda_t$ . Interpret this equation using the perturbations of the optimal path.

# Problem 3

## Question 3: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Combining  $[I_t]$  and  $[K_{t+1}]$ :

# Problem 3

## Question 3: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Combining  $[I_t]$  and  $[K_{t+1}]$ :

$$\beta^t \left( 1 + \phi \frac{I_t}{K_t} \right) = \beta^{t+1} \left( \alpha A_{t+1} K_{t+1}^{\alpha-1} + \frac{\phi}{2} \frac{I_{t+1}^2}{K_{t+1}^2} \right) + (1 - \delta) \beta^{t+1} \left( 1 + \phi \frac{I_{t+1}}{K_{t+1}} \right)$$



# Problem 3

## Question 3: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Combining  $[I_t]$  and  $[K_{t+1}]$ :

$$\beta^t \left( 1 + \phi \frac{I_t}{K_t} \right) = \beta^{t+1} \left( \alpha A_{t+1} K_{t+1}^{\alpha-1} + \frac{\phi}{2} \frac{I_{t+1}^2}{K_{t+1}^2} \right) + (1 - \delta) \beta^{t+1} \left( 1 + \phi \frac{I_{t+1}}{K_{t+1}} \right)$$

$$\iff 1 + \phi \frac{I_t}{K_t} = \beta \left( \alpha A_{t+1} K_{t+1}^{\alpha-1} + \frac{\phi}{2} \frac{I_{t+1}^2}{K_{t+1}^2} \right) + (1 - \delta) \beta \left( 1 + \phi \frac{I_{t+1}}{K_{t+1}} \right).$$

# Problem 3

## Question 3: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- **Perturbation argument:** Suppose the firm increases  $I_t$  by  $dI_t = \Delta > 0$ , returning to the optimal trajectory in  $t + 2$ .

# Problem 3

## Question 3: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- **Perturbation argument:** Suppose the firm increases  $I_t$  by  $dI_t = \Delta > 0$ , returning to the optimal trajectory in  $t + 2$ .

- $dI_t = \Delta \implies d\psi_t = \left(1 + \phi \frac{I_t}{K_t}\right) dI_t = \left(1 + \phi \frac{I_t}{K_t}\right) \Delta > 0$ , where  
 $\psi_t = I_t + \frac{\phi}{2} \frac{I_t^2}{K_t}$ .

# Problem 3

## Question 3: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- **Perturbation argument:** Suppose the firm increases  $I_t$  by  $dI_t = \Delta > 0$ , returning to the optimal trajectory in  $t + 2$ .

- $dI_t = \Delta \implies d\psi_t = \left(1 + \phi \frac{I_t}{K_t}\right) dI_t = \left(1 + \phi \frac{I_t}{K_t}\right) \Delta > 0$ , where  $\psi_t = I_t + \frac{\phi}{2} \frac{I_t^2}{K_t}$ .

- $dI_t = \Delta \implies dK_{t+1} = \Delta$ . Thus,  $d\pi_{t+1} = \frac{\partial \pi_{t+1}}{\partial K_{t+1}} dK_{t+1} = \alpha A_{t+1} K_{t+1}^{\alpha-1} \Delta > 0$ , where  $\pi_t = A_t K_t^\alpha$ .

# Problem 3

## Question 3: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Returning to the optimal trajectory in  $t + 2$  means leaving  $K_{t+2}$  unchanged, i.e.,  $dK_{t+2} = 0$ . Therefore,

$$\underbrace{dK_{t+2}}_0 = (1 - \delta) \underbrace{dK_{t+1}}_{\Delta} + dI_{t+1} \iff dI_{t+1} = -(1 - \delta)\Delta < 0.$$

# Problem 3

## Question 3: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Returning to the optimal trajectory in  $t + 2$  means leaving  $K_{t+2}$  unchanged, i.e.,  $dK_{t+2} = 0$ . Therefore,

$$\underbrace{dK_{t+2}}_0 = (1 - \delta) \underbrace{dK_{t+1}}_{\Delta} + dI_{t+1} \iff dI_{t+1} = -(1 - \delta)\Delta < 0.$$

- $dK_{t+1} = \Delta$  and  $dI_{t+1} = -(1 - \delta)\Delta \implies$   
 $d\psi_{t+1} = -(1 - \delta)\left(1 + \phi \frac{I_{t+1}}{K_{t+1}}\right) \Delta - \frac{\phi}{2} \frac{I_{t+1}^2}{K_{t+1}^2} \Delta < 0$

# Problem 3

## Question 3: Solution

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Returning to the optimal trajectory in  $t + 2$  means leaving  $K_{t+2}$  unchanged, i.e.,  $dK_{t+2} = 0$ . Therefore,

$$\underbrace{dK_{t+2}}_0 = (1 - \delta) \underbrace{dK_{t+1}}_{\Delta} + dI_{t+1} \iff dI_{t+1} = -(1 - \delta)\Delta < 0.$$

- $dK_{t+1} = \Delta$  and  $dI_{t+1} = -(1 - \delta)\Delta \implies$   
 $d\psi_{t+1} = -(1 - \delta)\left(1 + \phi \frac{I_{t+1}}{K_{t+1}}\right) \Delta - \frac{\phi}{2} \frac{I_{t+1}^2}{K_{t+1}^2} \Delta < 0$
- Combining all these costs and benefits and requiring that the perturbation is not profitable, we get the Euler equation.

# Problem 3

## Question 4

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

4. Rewrite the capital law of motion for an arbitrary length of period  $\Delta$ . Obtain the continuous-time version of the optimization problem.



# Problem 3

## Question 4

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Note that  $K_{t+1}$  is a **stock** variable while  $I_t$  is a **flow**, just as depreciation  $\delta K_t$  and profits  $A_t K_t^\alpha$ .

# Problem 3

## Question 4

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Note that  $K_{t+1}$  is a **stock** variable while  $I_t$  is a **flow**, just as depreciation  $\delta K_t$  and profits  $A_t K_t^\alpha$ .
- Let  $\beta \equiv e^{-r}$ . Then,

# Problem 3

## Question 4

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Note that  $K_{t+1}$  is a **stock** variable while  $I_t$  is a **flow**, just as depreciation  $\delta K_t$  and profits  $A_t K_t^\alpha$ .
- Let  $\beta \equiv e^{-r}$ . Then,

$$K_{t+\Delta} = (1 - \delta\Delta)K_t + I_t\Delta$$

# Problem 3

## Question 4

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Note that  $K_{t+1}$  is a **stock** variable while  $I_t$  is a **flow**, just as depreciation  $\delta K_t$  and profits  $A_t K_t^\alpha$ .
- Let  $\beta \equiv e^{-r}$ . Then,

$$K_{t+\Delta} = (1 - \delta\Delta)K_t + I_t\Delta$$

$$\iff K_{t+\Delta} - K_t = (I_t - \delta K_t)\Delta$$

# Problem 3

## Question 4

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Note that  $K_{t+1}$  is a **stock** variable while  $I_t$  is a **flow**, just as depreciation  $\delta K_t$  and profits  $A_t K_t^\alpha$ .
- Let  $\beta \equiv e^{-r}$ . Then,

$$K_{t+\Delta} = (1 - \delta\Delta)K_t + I_t\Delta$$

$$\Longleftrightarrow K_{t+\Delta} - K_t = (I_t - \delta K_t)\Delta$$

$$\implies \dot{K}_t \equiv \lim_{\Delta \rightarrow 0} \frac{K_{t+\Delta} - K_t}{\Delta} = I_t - \delta K_t.$$

# Problem 3

## Question 4

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- The Objective function is

$$\int_0^{\infty} e^{-rt} \left( A_t K_t^{\alpha} - I_t - \frac{\phi}{2} \frac{I_t^2}{K_t} \right) dt.$$

# Problem 3

## Question 5

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

5. Define the Hamiltonian and write down the optimality conditions.

# Problem 3

## Question 5

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Hamiltonian:

$$\mathcal{H}_t = e^{-rt} \left( A_t K_t^\alpha - I_t - \frac{\phi}{2} \frac{I_t^2}{K_t} \right) + \lambda_t (I_t - \delta K_t),$$

where  $\lambda_t$  is the co-state variable.



# Problem 3

## Question 5

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Hamiltonian:

$$\mathcal{H}_t = e^{-rt} \left( A_t K_t^\alpha - I_t - \frac{\phi}{2} \frac{I_t^2}{K_t} \right) + \lambda_t (I_t - \delta K_t),$$

where  $\lambda_t$  is the co-state variable.

- Optimality conditions:

$$[I_t] \quad \frac{\partial \mathcal{H}_t}{\partial I_t} = 0 \iff -e^{-rt} \left( 1 + \phi \frac{I_t}{K_t} \right) + \lambda_t = 0$$

$$[K_t] \quad \frac{\partial \mathcal{H}_t}{\partial K_t} = -\dot{\lambda}_t \iff e^{-rt} \left( \alpha A_t K_t^{\alpha-1} + \phi \frac{I_t^2}{K_t^2} \right) - \delta \lambda_t = -\dot{\lambda}_t$$

# Problem 3

## Question 6

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

6. Show that the same continuous-time optimality conditions can be obtained directly from the optimality conditions in discrete time.

# Problem 3

## Question 6

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Rewriting the FOC of the discrete-time problem for an arbitrary length of period  $\Delta$ ,

$$[I_t] \quad -e^{-rt} \left( 1 + \phi \frac{I_t}{K_t} \right) \Delta + \lambda_t \Delta = 0$$

$$\iff -e^{-rt} \left( 1 + \phi \frac{I_t}{K_t} \right) + \lambda_t = 0$$

$$[K_{t+1}]$$

$$-\lambda_t + e^{-r(t+\Delta)} \left( \alpha A_{t+\Delta} K_{t+\Delta}^{\alpha-1} + \frac{\phi}{2} \frac{I_{t+\Delta}^2}{K_{t+\Delta}^2} \right) \Delta + \lambda_{t+\Delta} (1 - \delta \Delta) = 0$$

$$\iff e^{-r(t+\Delta)} \left( \alpha A_{t+\Delta} K_{t+\Delta}^{\alpha-1} + \frac{\phi}{2} \frac{I_{t+\Delta}^2}{K_{t+\Delta}^2} \right) - \delta \lambda_{t+\Delta} = -\frac{\lambda_{t+\Delta} - \lambda_t}{\Delta}$$

# Problem 3

## Question 6

Class #1

EC400: DPDE

Problem 1

Problem 2

Problem 3

- Finally, taking limits as  $\Delta \rightarrow 0$ , we obtain the same optimality conditions from question 5.

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# Appendix

# Problem 1, Question 3: Details

Class #1

EC400: DPDE

Appendix

Write the BC for  $t \in \{0, \dots, T\}$  as  $B_t = R^{-1}(B_{t+1} - Y_t + C_t)$ , evaluate at  $t = 0$ , and iterate forward:

$$B_0 = R^{-1}(B_1 - Y_0 + C_0)$$

# Problem 1, Question 3: Details

Class #1

EC400: DPDE

Appendix

Write the BC for  $t \in \{0, \dots, T\}$  as  $B_t = R^{-1}(B_{t+1} - Y_t + C_t)$ , evaluate at  $t = 0$ , and iterate forward:

$$B_0 = R^{-1}(B_1 - Y_0 + C_0)$$

$$= R^{-1}[R^{-1}(B_2 - Y_1 + C_1) - Y_0 + C_0]$$

# Problem 1, Question 3: Details

Class #1

EC400: DPDE

Appendix

Write the BC for  $t \in \{0, \dots, T\}$  as  $B_t = R^{-1}(B_{t+1} - Y_t + C_t)$ , evaluate at  $t = 0$ , and iterate forward:

$$\begin{aligned} B_0 &= R^{-1}(B_1 - Y_0 + C_0) \\ &= R^{-1}[R^{-1}(B_2 - Y_1 + C_1) - Y_0 + C_0] \\ &= R^{-2}B_2 + R^{-2}(C_1 - Y_1) + R^{-1}(C_0 - Y_0) \end{aligned}$$



# Problem 1, Question 3: Details

Class #1

EC400: DPDE

Appendix

Write the BC for  $t \in \{0, \dots, T\}$  as  $B_t = R^{-1}(B_{t+1} - Y_t + C_t)$ , evaluate at  $t = 0$ , and iterate forward:

$$B_0 = R^{-1}(B_1 - Y_0 + C_0)$$

$$= R^{-1}[R^{-1}(B_2 - Y_1 + C_1) - Y_0 + C_0]$$

$$= R^{-2}B_2 + R^{-2}(C_1 - Y_1) + R^{-1}(C_0 - Y_0)$$

$$= R^{-2}[R^{-1}(B_3 - Y_2 + C_2)] + R^{-2}(C_1 - Y_1) + R^{-1}(C_0 - Y_0)$$

# Problem 1, Question 3: Details

Class #1

EC400: DPDE

Appendix

Write the BC for  $t \in \{0, \dots, T\}$  as  $B_t = R^{-1}(B_{t+1} - Y_t + C_t)$ , evaluate at  $t = 0$ , and iterate forward:

$$B_0 = R^{-1}(B_1 - Y_0 + C_0)$$

$$= R^{-1}[R^{-1}(B_2 - Y_1 + C_1) - Y_0 + C_0]$$

$$= R^{-2}B_2 + R^{-2}(C_1 - Y_1) + R^{-1}(C_0 - Y_0)$$

$$= R^{-2}[R^{-1}(B_3 - Y_2 + C_2)] + R^{-2}(C_1 - Y_1) + R^{-1}(C_0 - Y_0)$$

$$= R^{-3}B_3 + R^{-3}(C_2 - Y_2) + R^{-2}(C_1 - Y_1) + R^{-1}(C_0 - Y_0)$$

# Problem 1, Question 3: Details

Class #1

EC400: DPDE

Appendix

Write the BC for  $t \in \{0, \dots, T\}$  as  $B_t = R^{-1}(B_{t+1} - Y_t + C_t)$ , evaluate at  $t = 0$ , and iterate forward:

$$\begin{aligned} B_0 &= R^{-1}(B_1 - Y_0 + C_0) \\ &= R^{-1}[R^{-1}(B_2 - Y_1 + C_1) - Y_0 + C_0] \\ &= R^{-2}B_2 + R^{-2}(C_1 - Y_1) + R^{-1}(C_0 - Y_0) \\ &= R^{-2}[R^{-1}(B_3 - Y_2 + C_2)] + R^{-2}(C_1 - Y_1) + R^{-1}(C_0 - Y_0) \\ &= R^{-3}B_3 + R^{-3}(C_2 - Y_2) + R^{-2}(C_1 - Y_1) + R^{-1}(C_0 - Y_0) \\ &\vdots \\ &= R^{-1}\left[R^{-T}B_{T+1} + \sum_{t=0}^T R^{-t}(C_t - Y_t)\right]. \end{aligned}$$

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● Thus,

$$RB_0 = R^{-T} B_{T+1} + \sum_{t=0}^T R^{-t} (C_t - Y_t).$$

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● Thus,

$$RB_0 = R^{-T} B_{T+1} + \sum_{t=0}^T R^{-t} (C_t - Y_t).$$

● Finally, use the assumptions  $B_0 = 0$  and  $Y_t = Y \forall t \in \{0, \dots, T\}$  to obtain

$$0 = R^{-T} B_{T+1} + \sum_{t=0}^T R^{-t} (C_t - Y).$$

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- Just iterate backward the Euler equation:

# Problem 1, Question 3: Details

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- Just iterate backward the Euler equation:

$$C_t = R\beta C_{t-1}$$

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- Just iterate backward the Euler equation:

$$\begin{aligned}C_t &= R\beta C_{t-1} \\ &= R\beta (R\beta C_{t-2})\end{aligned}$$



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- Just iterate backward the Euler equation:

$$\begin{aligned}C_t &= R\beta C_{t-1} \\&= R\beta (R\beta C_{t-2}) \\&= (R\beta)^2 C_{t-2}\end{aligned}$$

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- Just iterate backward the Euler equation:

$$C_t = R\beta C_{t-1}$$

$$= R\beta (R\beta C_{t-2})$$

$$= (R\beta)^2 C_{t-2}$$

$$= (R\beta)^2 (R\beta C_{t-3})$$

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- Just iterate backward the Euler equation:

$$C_t = R\beta C_{t-1}$$

$$= R\beta (R\beta C_{t-2})$$

$$= (R\beta)^2 C_{t-2}$$

$$= (R\beta)^2 (R\beta C_{t-3})$$

$$= (R\beta)^3 C_{t-3}$$

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- Just iterate backward the Euler equation:

$$\begin{aligned}C_t &= R\beta C_{t-1} \\&= R\beta (R\beta C_{t-2}) \\&= (R\beta)^2 C_{t-2} \\&= (R\beta)^2 (R\beta C_{t-3}) \\&= (R\beta)^3 C_{t-3} \\&\vdots \\&= (R\beta)^t C_{t-t}.\end{aligned}$$

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- Just iterate backward the Euler equation:

$$\begin{aligned}C_t &= R\beta C_{t-1} \\&= R\beta (R\beta C_{t-2}) \\&= (R\beta)^2 C_{t-2} \\&= (R\beta)^2 (R\beta C_{t-3}) \\&= (R\beta)^3 C_{t-3} \\&\vdots \\&= (R\beta)^t C_{t-t}.\end{aligned}$$

- Finally, plug the resulting expression for  $C_T$  ( $C_0$ ) into the terminal condition to obtain  $B_{T+1} = \eta (R\beta)^T C_0$ .

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- Plugging in the expressions for  $C_t(C_0)$  and  $B_{T+1}(C_0)$  into the budget constraint:

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- Plugging in the expressions for  $C_t (C_0)$  and  $B_{T+1} (C_0)$  into the budget constraint:

$$R^{-1} \left[ R^{-T} \eta (R\beta)^T C_0 + \sum_{t=0}^T R^{-t} [(R\beta)^t C_0 - Y] \right] = 0$$

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- Plugging in the expressions for  $C_t (C_0)$  and  $B_{T+1} (C_0)$  into the budget constraint:

$$R^{-1} \left[ R^{-T} \eta (R\beta)^T C_0 + \sum_{t=0}^T R^{-t} [(R\beta)^t C_0 - Y] \right] = 0$$

$$\iff \eta \beta^T C_0 + C_0 \sum_{t=0}^T \beta^t - Y \sum_{t=0}^T R^{-t} = 0$$



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- Plugging in the expressions for  $C_t (C_0)$  and  $B_{T+1} (C_0)$  into the budget constraint:

$$R^{-1} \left[ R^{-T} \eta (R\beta)^T C_0 + \sum_{t=0}^T R^{-t} [(R\beta)^t C_0 - Y] \right] = 0$$

$$\iff \eta \beta^T C_0 + C_0 \sum_{t=0}^T \beta^t - Y \sum_{t=0}^T R^{-t} = 0$$

$$\iff \eta \beta^T C_0 + C_0 \frac{1 - \beta^{T+1}}{1 - \beta} - Y \frac{1 - R^{-(T+1)}}{1 - R^{-1}} = 0$$

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- Plugging in the expressions for  $C_t (C_0)$  and  $B_{T+1} (C_0)$  into the budget constraint:

$$R^{-1} \left[ R^{-T} \eta (R\beta)^T C_0 + \sum_{t=0}^T R^{-t} [(R\beta)^t C_0 - Y] \right] = 0$$

$$\Leftrightarrow \eta \beta^T C_0 + C_0 \sum_{t=0}^T \beta^t - Y \sum_{t=0}^T R^{-t} = 0$$

$$\Leftrightarrow \eta \beta^T C_0 + C_0 \frac{1 - \beta^{T+1}}{1 - \beta} - Y \frac{1 - R^{-(T+1)}}{1 - R^{-1}} = 0$$

$$\Leftrightarrow C_0 \frac{1 - \beta^{T+1} + (1 - \beta) \eta \beta^T}{1 - \beta} = Y \frac{R (1 - R^{-(T+1)})}{R - 1}$$

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- Plugging in the expressions for  $C_t (C_0)$  and  $B_{T+1} (C_0)$  into the budget constraint:

$$R^{-1} \left[ R^{-T} \eta (R\beta)^T C_0 + \sum_{t=0}^T R^{-t} [(R\beta)^t C_0 - Y] \right] = 0$$

$$\iff \eta \beta^T C_0 + C_0 \sum_{t=0}^T \beta^t - Y \sum_{t=0}^T R^{-t} = 0$$

$$\iff \eta \beta^T C_0 + C_0 \frac{1 - \beta^{T+1}}{1 - \beta} - Y \frac{1 - R^{-(T+1)}}{1 - R^{-1}} = 0$$

$$\iff C_0 \frac{1 - \beta^{T+1} + (1 - \beta)\eta \beta^T}{1 - \beta} = Y \frac{R(1 - R^{-(T+1)})}{R - 1}$$

$$\iff C_0 = \frac{1 - \beta}{1 + \eta \beta^T - (1 + \eta)\beta^{T+1}} \frac{R - R^{-T}}{R - 1} Y.$$

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- Rewrite the differential equation

$$\frac{\dot{C}_t}{C_t} = (r - \rho) \iff \frac{1}{C_t} dC_t = (r - \rho) dt$$

and integrate on both sides to obtain

$$\kappa + \ln(C_t) = \psi + (r - \rho)t$$

$$\iff C_t = C_0 e^{(r-\rho)t},$$

where  $\kappa$  and  $\psi$  are the constants of integration and  $C_0 \equiv e^{\psi - \kappa}$ .

◀ return

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● FOC:

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● FOC:

$$\frac{-\rho e^{-\rho T^*}}{1 - e^{-\rho T^*}} \left[ 1 - e^{-\rho T^*} \right] + \left[ \ln(\rho B_0) - \ln(1 - e^{-\rho T^*}) \right] \rho e^{-\rho T^*} = 0$$

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● FOC:

$$\frac{-\rho e^{-\rho T^*}}{1 - e^{-\rho T^*}} \left[ 1 - e^{-\rho T^*} \right] + \left[ \ln(\rho B_0) - \ln(1 - e^{-\rho T^*}) \right] \rho e^{-\rho T^*} = 0$$

$$\iff \ln(1 - e^{-\rho T^*}) = \ln(\rho B_0 e^{-1})$$

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● FOC:

$$\frac{-\rho e^{-\rho T^*}}{1 - e^{-\rho T^*}} \left[ 1 - e^{-\rho T^*} \right] + \left[ \ln(\rho B_0) - \ln(1 - e^{-\rho T^*}) \right] \rho e^{-\rho T^*} = 0$$

$$\iff \ln(1 - e^{-\rho T^*}) = \ln(\rho B_0 e^{-1})$$

$$\iff e^{-\rho T^*} = 1 - \rho B_0 e^{-1}$$



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● FOC:

$$\frac{-\rho e^{-\rho T^*}}{1 - e^{-\rho T^*}} \left[ 1 - e^{-\rho T^*} \right] + \left[ \ln(\rho B_0) - \ln(1 - e^{-\rho T^*}) \right] \rho e^{-\rho T^*} = 0$$

$$\iff \ln(1 - e^{-\rho T^*}) = \ln(\rho B_0 e^{-1})$$

$$\iff e^{-\rho T^*} = 1 - \rho B_0 e^{-1}$$

$$\iff T^* = -\frac{1}{\rho} \ln(1 - \rho B_0 e^{-1}),$$

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● FOC:

$$\frac{-\rho e^{-\rho T^*}}{1 - e^{-\rho T^*}} \left[ 1 - e^{-\rho T^*} \right] + \left[ \ln(\rho B_0) - \ln(1 - e^{-\rho T^*}) \right] \rho e^{-\rho T^*} = 0$$

$$\iff \ln(1 - e^{-\rho T^*}) = \ln(\rho B_0 e^{-1})$$

$$\iff e^{-\rho T^*} = 1 - \rho B_0 e^{-1}$$

$$\iff T^* = -\frac{1}{\rho} \ln(1 - \rho B_0 e^{-1}),$$

which is well-defined as long as  $1 - \rho B_0 e^{-1} > 0 \iff \rho B_0 e^{-1} < 1$ .

◀ return

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$$du = e^{-\rho T} \ln(C_T) \Delta - \int_0^T \frac{e^{-\rho t}}{C_T} \frac{r C_T \Delta}{e^{rt} - 1} dt$$

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$$\begin{aligned} du &= e^{-\rho T} \ln(C_T) \Delta - \int_0^T \frac{e^{-\rho t}}{C_T} \frac{r C_T \Delta}{e^{rt} - 1} dt \\ &= e^{-\rho T} \ln(C_T) \Delta - \frac{r \Delta}{e^{rT} - 1} \frac{1 - e^{-\rho T}}{\rho} \end{aligned}$$

## Problem 2, Question 5: Details

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$$\begin{aligned} du &= e^{-\rho T} \ln(C_T) \Delta - \int_0^T \frac{e^{-\rho t}}{C_T} \frac{r C_T \Delta}{e^{rt} - 1} dt \\ &= e^{-\rho T} \ln(C_T) \Delta - \frac{r \Delta}{e^{rT} - 1} \frac{1 - e^{-\rho T}}{\rho} \\ &= e^{-\rho T} \ln(C_T) \Delta - \frac{1 - e^{-\rho T}}{\frac{1}{e^{-rT}} - 1} \Delta \end{aligned}$$

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$$\begin{aligned} du &= e^{-\rho T} \ln(C_T) \Delta - \int_0^T \frac{e^{-\rho t}}{C_T} \frac{r C_T \Delta}{e^{rt} - 1} dt \\ &= e^{-\rho T} \ln(C_T) \Delta - \frac{r \Delta}{e^{rT} - 1} \frac{1 - e^{-\rho T}}{\rho} \\ &= e^{-\rho T} \ln(C_T) \Delta - \frac{1 - e^{-\rho T}}{\frac{1}{e^{-rT}} - 1} \Delta \\ &= e^{-\rho T} \ln(C_T) \Delta - \frac{e^{-rT} (1 - e^{-\rho T})}{1 - e^{-rT}} \Delta \end{aligned}$$

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$$\begin{aligned} du &= e^{-\rho T} \ln(C_T) \Delta - \int_0^T \frac{e^{-\rho t}}{C_T} \frac{r C_T \Delta}{e^{rt} - 1} dt \\ &= e^{-\rho T} \ln(C_T) \Delta - \frac{r \Delta}{e^{rT} - 1} \frac{1 - e^{-\rho T}}{\rho} \\ &= e^{-\rho T} \ln(C_T) \Delta - \frac{1 - e^{-\rho T}}{\frac{1}{e^{-rT}} - 1} \Delta \\ &= e^{-\rho T} \ln(C_T) \Delta - \frac{e^{-rT} (1 - e^{-\rho T})}{1 - e^{-rT}} \Delta \\ &= e^{-\rho T} \left[ \ln(C_T) - 1 \right] \Delta. \end{aligned}$$